## **Sketch of Lecture 31** Tue, 03/18/2014

**Example 125.** Consider  $x' = \begin{pmatrix} 1 & -3 \\ 3 & 7 \end{pmatrix} x$ .

The characteristic polynomial  $(1 - \lambda)(7 - \lambda) + 9 = \lambda^2 - 8\lambda + 16 = (\lambda - 4)^2$  has the double root  $\lambda = 4$ . However,  $\begin{pmatrix} -3 & -3 \\ 3 & 3 \end{pmatrix}$   $v = 0$  has solution only  $v = c \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ −1 .

We say that the eigenvalue 4 is defective with defect 1 (number of missing eigenvectors).

So far, we have found the solution  $\boldsymbol{x}_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ −1  $\Big) e^{4t}$  but we are missing a second independent solution.  $\diamondsuit$ 

We want to solve  $x' = Ax$ . Suppose that  $\lambda$  is a repeated and defective eigenvalue.

- As a first attempt, we might try to look for a solution of the form  $x = wt e^{\lambda t}$ . Plugging into the DE, we get  $x' = we^{\lambda t} + w\lambda t e^{\lambda t} = Ax = Awt e^{\lambda t}$ . Setting  $t = 0$ , this implies  $w = 0$ which means our first attempt failed.
- Not giving up, we next look for a solution of the form  $x = ue^{\lambda t} + wte^{\lambda t}$ . Plugging into the DE, we now get  $\mathbf{x}' = \mathbf{u}\lambda e^{\lambda t} + \mathbf{w}e^{\lambda t} + \mathbf{w}\lambda t e^{\lambda t} = A\mathbf{x} = A\mathbf{u}e^{\lambda t} + A\mathbf{w}te^{\lambda t}$ . Equating coefficients, we find  $Aw = \lambda w$  and  $Au = \lambda u + w$ . Equivalently,  $(A - \lambda I)w = 0$  and  $(A - \lambda I)u = w$ .<br>[*u* will be called a generalized eigenvector of rank 2.]  $\left[\boldsymbol{u}\right]$  will be called a generalized eigenvector of rank 2.]

**Example.** (cont'd) Let us find u such that  $\begin{pmatrix} -3 & -3 \\ 3 & 3 \end{pmatrix} w = \begin{pmatrix} 1 & 0 \\ -1 & 0 \end{pmatrix}$ −1 .

Note that the second equation is  $-1$  times the first. Hence, setting  $w_2 = c$ , we get  $w_1 = -c - \frac{1}{3}$ . Any choice of c will give us a vector w that we need to construct a second solution. For instance, choosing  $c = 0$ , we get  $\boldsymbol{w}$  =  $(-1/3, 0)^T$ . This means that  $\boldsymbol{x}_2$  =  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ −1  $\left( \begin{array}{c} -1/3 \\ 0 \end{array} \right)$   $e^{4t}$  is a second independent solution of the DE.  $\diamondsuit$ 

This approach works whenever we have a defective eigenvalue of multiplicity 2.

The same idea leads to the concept of generalized eigenvectors.

**Definition 126.**  $v_1, ..., v_k$  form a chain of generalized eigenvectors for the eigenvalue  $\lambda$  if

$$
(A - \lambda I)\mathbf{v}_1 = 0 \qquad \text{[solution of } \mathbf{x}' = A\mathbf{x}: \mathbf{v}_1 e^{\lambda t}]
$$
  
\n
$$
(A - \lambda I)\mathbf{v}_2 = \mathbf{v}_1 \qquad \text{[solution: } (\mathbf{v}_1 t + \mathbf{v}_2) e^{\lambda t}]
$$
  
\n
$$
(A - \lambda I)\mathbf{v}_3 = \mathbf{v}_2 \qquad \text{[solution: } \left(\mathbf{v}_1 \frac{t^2}{2} + \mathbf{v}_2 t + \mathbf{v}_3\right) e^{\lambda t}\right]
$$
  
\n
$$
\vdots
$$
  
\n
$$
(A - \lambda I)\mathbf{v}_k = \mathbf{v}_{k-1} \qquad \text{[solution: } \left(\mathbf{v}_1 \frac{t^{k-1}}{(k-1)!} + \mathbf{v}_2 \frac{t^{k-2}}{(k-2)!} + \dots \mathbf{v}_{k-1} t + \mathbf{v}_k\right) e^{\lambda t}\right]
$$

Some comments on generalized eigenvectors:

- Note that  $v_k$  satisfies  $(A \lambda I)^k v_k = 0$  but  $(A \lambda I)^{k-1} v_k = v_1 \neq 0$ . We say  $v_k$  is a generalized eigenvector of rank k.
- The vectors in several chains are independent if and only if the chains are based on independent eigenvectors (the  $v_1$ 's).
- For every  $n \times n$  matrix A, we can find n independent generalized eigenvectors. In particular, we can then find the general solution of  $x' = Ax$  by constructing the corresponding solutions as indicated above.