## <span id="page-0-2"></span>**Sketch of Lecture 32** Wed, 03/19/2014

**Review.** generalized eigenvectors and corresponding solutions to  $x' = Ax$ 

Recipe for solving  $\mathbf{x}' = A\mathbf{x}$ :

- find eigenvalues  $\lambda$ <br>• for each  $\lambda$ , find eig
- for each  $\lambda$ , find eigenvectors<br>• if  $\lambda$  is defective, find enough
- if  $\lambda$  is defective, find enough chains<sup>21</sup>
- if  $\lambda = a \pm bi$  is complex, take real and imaginary part of the solutions found  $\diamondsuit$

**Example 127.** Find the general solution of  $x' = \left(\frac{1}{x}\right)^{x}$  $\mathcal{L}$ 0 1 2  $-5$   $-3$   $-7$ 1 0 0 \.  $\big|x\big|$ .

**Solution.** The characteristic polynomial is  $\ldots = -(\lambda + 1)^3$ . Hence,  $\lambda = -1$  is an eigenvalue of multiplicity 3.

## We first solve for eigenvectors: 1 1 2 0  $\begin{array}{ccc} -5 & -2 & -7 \ 1 & 0 & \frac{1}{r_2+5r_1} \\ 1 & 0 & 1 \end{array}$ 1 1 2 0 0 3 3 0  $0 \ -1 \ -1 \ 0 \ \ \ \ \frac{r_2/3}{3r_3+r_2}$ 1 1 2 0 0 1 1 0 0 0 0 0

Setting  $v_3 = c$ , we get  $v_2 = -c$  and then  $v_1 = -c$ . The choice  $c = -1$  gives  $v_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$  $\mathcal{L}$ 1 1 −1 we get  $v_2 = -c$  and then  $v_1 = -c$ . The choice  $c = -1$  gives  $\mathbf{v}_1 = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$ . The corresponding solution is  $\boldsymbol{x}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  $\begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-t}.$ 

Since there was only one degree of freedom, there is no other independent eigenvector.  $\lambda = -1$  has defect 2. Because there is only one eigenvector to build a chain upon, we now know that there has to be a chain  $v_1, v_2$ ,  $v_3$  of three generalized eigenvectors.

To find  $\boldsymbol{v}_2$ , we need to solve  $\Big($  $\mathcal{L}$ 1 1 2  $\begin{bmatrix} -5 & -2 & -7 \\ 1 & 0 & 1 \end{bmatrix}$  $\Big) v_2 \!=\! \Big($  $\mathcal{L}$ 1 1 −1 . We can save time and effort by reusing the elimination 1 1 2 0 1 1 1 2 0 1 1 1 2 0 1

we have already done:  $\begin{bmatrix} -5 & -2 & -7 \end{bmatrix}$  0 1 1 0 1 0 −1  $\frac{r_2+5r_1}{r_3-r_1}$ 0 3 3 0 6  $\begin{array}{ccc|c} 0 & -1 & -1 & 0 & -2 & \frac{r_2}{3} \\ 0 & -2 & \frac{3r_3+r_2}{3} \end{array}$ 0 1 1 0 2 0 0 0 0 0

This time,  $v_3 = c$  leads to  $v_2 = 2 - c$ .  $v_1 + v_2 + 2v_3 = 1$  then gives  $v_1 = -1 - c$ . Hence,  $v_2 =$  $\mathcal{L}$  $-1-c$  $\frac{2-c}{c}$ This time,  $v_3 = c$  leads to  $v_2 = 2 - c$ .  $v_1 + v_2 + 2v_3 = 1$  then gives  $v_1 = -1 - c$ . Hence,  $v_2 = \begin{pmatrix} -1 - c \\ 2 - c \\ c \end{pmatrix} =$  $\mathcal{L}$  $\frac{-1}{2}$ 0  $+ c \left( \begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right)$ Ί −1  $\frac{-1}{1}$ . Note that the second summand is just an eigenvector! We can choose any c. For instance,  $\lceil$  ( 1 Τ 1

choosing  $c = 0$  gives  $v_2 =$  $\overline{1}$  $\frac{-1}{2}$ 0 with corresponding solution<sup>22</sup>  $x_2 =$  $\mathcal{L}$ 1 −1  $\left.\right)$ t +  $\left(\right.$  $\overline{1}$  $\frac{-1}{2}$ 0  $\overline{1}$  $e^{-t}$ .

Finally, to find  $v_3$  we have to solve  $(A - \lambda I)v_3 = v_2$ . We can again reuse the elimination we have already done:  $\frac{1}{2}$   $\frac{1}{2}$   $\frac{2}{2}$   $\frac{0}{2}$   $\frac{1}{2}$   $\frac{-1}{2}$  $\begin{array}{ccc} -5 & -2 & -7 & 0 & 1 & 2 \ 1 & 0 & 1 & 0 & -1 & 0 \ \end{array}$   $\begin{array}{ccc} \overrightarrow{r_2+5r_1} \\ \overrightarrow{r_3-r_1} \end{array}$  $\begin{array}{ccc} 1 & 1 & 2 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{array}$  $\begin{array}{ccc|ccc}\n0 & 3 & 3 & 0 & 6 & -3 \\
\hline\n0 & 0 & 3 & 3 & 0\n\end{array}$  $\begin{array}{ccc|c} 0 & -1 & -1 & 0 & -2 & 1 & \frac{r_2/3}{3r_3+r_2} \end{array}$  $\begin{array}{|c|c|c|c|c|c|c|c|} \hline 1 & 1 & 2 & 0 & 1 & -1 \\ \hline 0 & 1 & 1 & 0 & 0 & 1 \\ \hline \end{array}$  $\begin{array}{ccc|c} 0 & 1 & 1 & 0 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array}$ 

As before,  $v_3 = c$  leads to  $v_2 = -1 - c$ .  $v_1 + v_2 + 2v_3 = -1$  then gives  $v_1 = -c$ . Choosing  $c = 0$ , we get  $\boldsymbol{v}_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$  $\mathcal{L}$ 0  $\frac{-1}{0}$  $\setminus$  $\overline{1}$ which gives us the solution<sup>23</sup>  $x_3 =$  $\lceil$  (  $\mathcal{L}$ 1 1 −1  $\setminus$ T  $t^2$  $rac{t^2}{2} + \Bigg($  $\mathcal{L}$  $\frac{-1}{2}$ 0  $\left.\right)$ t +  $\left(\right.$  $\mathcal{L}$ 0  $\frac{-1}{0}$ Τ  $\overline{1}$ 1  $e^{-t}$ .  $\diamondsuit$ 

## **Example 128.** Suppose we have an eigenvalue  $\lambda$  of multiplicity 5.

Here are the 7 possibilities for chains, listed by the lengths of the chains that occur:

- $(\text{defect } 0) \; 1, 1, 1, 1, 1$  [i.e., 5 eigenvectors]
- $(\text{defect } 1)$  2, 1, 1, 1
- $(\text{defect 2})$  2, 2, 1 or 3, 1, 1
- $(\text{defect } 3)$  3, 2 or 4, 1
- $(\text{defect } 4)$  5

Note that the defect is something we know (after computing the eigenvectors). We have seen how to do the defect 0 and defect 4 cases; the other ones are a little bit more intricate.

<span id="page-0-1"></span><span id="page-0-0"></span>

[<sup>21.</sup>](#page-0-0) These computations can become a bit intricate. For exams, we will content ourselves with the defective cases involving a single chain (per eigenvalue) only.

[<sup>22.</sup>](#page-0-1) How does choosing a different c affect the solution  $x_2$ . Why does it not make a difference?

[<sup>23.</sup>](#page-0-2) Try and see what happens if you went looking for a fourth vector  $v_4$  in the chain. Why does it fail?