

Inhomogeneous linear systems

$\mathbf{x}' = A\mathbf{x} + \mathbf{f}(t)$ is the general form of a (first-order²⁵) inhomogeneous system of linear DEs.

- To solve it, we find a particular solution $\mathbf{x}_p(t)$.
- Then, the general solution is $\mathbf{x}(t) = \mathbf{x}_p(t) + \mathbf{x}_c(t)$.
Here, $\mathbf{x}_c(t)$ is the general solution of $\mathbf{x}' = A\mathbf{x}$.
- Two methods: **undetermined coefficients** and **variation of constants**

Example 137. Find the general solution of $\mathbf{x}' = \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} \mathbf{x} + \begin{pmatrix} 0 \\ -2e^{3t} \end{pmatrix}$.

Solution. From the previous lecture, we know that $\mathbf{x}_c = c_1 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 3 \\ 2 \end{pmatrix} e^{4t}$.

We look for a solution of the shape $\mathbf{x}_p = \mathbf{a}e^{3t}$. To determine the **undetermined coefficients**, we plug into the DE.

$$\mathbf{x}'_p = 3\mathbf{a}e^{3t} \stackrel{!}{=} \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} \mathbf{a}e^{3t} + \begin{pmatrix} 0 \\ -2e^{3t} \end{pmatrix} = \begin{pmatrix} 2a_1 + 3a_2 \\ 2a_1 + a_2 - 2 \end{pmatrix} e^{3t}$$

Solving $\begin{pmatrix} 3a_1 \\ 3a_2 \end{pmatrix} = \begin{pmatrix} 2a_1 + 3a_2 \\ 2a_1 + a_2 - 2 \end{pmatrix}$, we find $\mathbf{a} = \begin{pmatrix} 3/2 \\ 1/2 \end{pmatrix}$.

Hence, the general solution is $\begin{pmatrix} 3/2 \\ 1/2 \end{pmatrix} e^{3t} + c_1 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-t} + c_2 \begin{pmatrix} 3 \\ 2 \end{pmatrix} e^{4t}$. ◇

Example 138. Find a particular solution of $\mathbf{x}' = \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} \mathbf{x} + \begin{pmatrix} 2e^{4t} \\ e^{4t} \end{pmatrix}$.

Solution. Duplication! The 4 (“new” root) from e^{4t} in the inhomogeneous part coincides with an eigenvalue (“old” root). In our particular solution, we therefore include a term $\mathbf{a}te^{4t}$. However, that is not enough; as in the case of generalized eigenvectors, we need to include lower order terms as well.

Hence, we look for a solution of the form $\mathbf{x}_p = (\mathbf{a}t + \mathbf{b})e^{4t}$. To determine \mathbf{a} and \mathbf{b} , we plug into the differential equation. (Note that \mathbf{b} will not be unique: if \mathbf{b} works, then so does any $\mathbf{b} + c \begin{pmatrix} 3 \\ 2 \end{pmatrix}$. Why?!)

$$\mathbf{x}'_p = (4\mathbf{a}t + \mathbf{a} + 4\mathbf{b})e^{4t} \stackrel{!}{=} \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} (\mathbf{a}t + \mathbf{b})e^{4t} + \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^{4t}$$

Equating the coefficients of te^{4t} , we get $4\mathbf{a} = \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} \mathbf{a}$ or, equivalently, $\begin{pmatrix} 2a_1 - 3a_2 \\ -2a_1 + 3a_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$.

Equating the coefficients of e^{4t} , we get $\mathbf{a} + 4\mathbf{b} = \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} \mathbf{b} + \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ or, equivalently, $\begin{pmatrix} a_1 + 2b_1 - 3b_2 \\ a_2 - 2b_1 + 3b_2 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$.

Adding the last two equations, we get $a_1 + a_2 = 3$. Together with $2a_1 - 3a_2 = 0$, this gives $\mathbf{a} = \begin{pmatrix} 9/5 \\ 6/5 \end{pmatrix}$.

We are left with $2b_1 - 3b_2 = 2 - a_1 = \frac{1}{5}$. We choose $b_2 = 0$, in which case we find $b_1 = \frac{1}{10}$.

In conclusion, we have found the particular solution $\mathbf{x}_p = \begin{pmatrix} 9/5t + 1/10 \\ 6/5t \end{pmatrix} e^{4t}$. ◇

Example 139. Find a particular solution of $\mathbf{x}' = \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} \mathbf{x} + \begin{pmatrix} 2e^{4t} \\ e^{4t} - 2e^{3t} \end{pmatrix}$.

Solution. Note that $\begin{pmatrix} 2e^{4t} \\ e^{4t} + e^{3t} \end{pmatrix} = \begin{pmatrix} 2e^{4t} \\ e^{4t} \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 0 \\ -2e^{3t} \end{pmatrix}$.

Using the particular solutions from the two previous examples, we therefore have the particular solution

$$\mathbf{x}_p = \begin{pmatrix} 9/5t + 1/10 \\ 6/5t \end{pmatrix} e^{4t} - \frac{1}{2} \begin{pmatrix} 3/2 \\ 1/2 \end{pmatrix} e^{3t}$$
 ◇

25. Recall that any system can be written as a (larger) first-order system.