

Review for Midterm 3

- Bring a **number 2 pencil** to the exam!
- **Extra help session:** today and tomorrow, **4–7pm**, in AH 441
- Room assignments for Thursday, Nov 20, 7-8:15pm:
 - if your last name starts with A-E: 213 Greg Hall
 - if your last name starts with F-L: 100 Greg Hall
 - if your last name starts with M-Sh: 66 Library
 - if your last name starts with Si-Z: 103 Mumford Hall
- Big topics:
 - Orthogonal projections
 - Least squares
 - Gram–Schmidt
 - Determinants
 - Eigenvalues and eigenvectors

Orthogonal projections

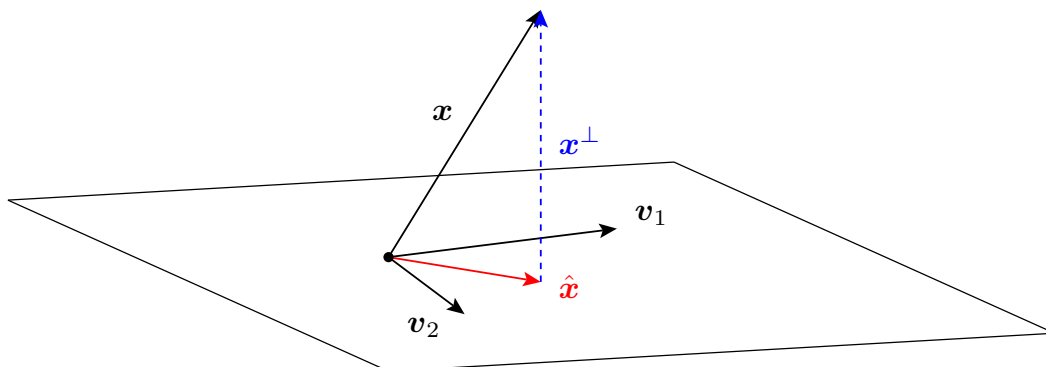
- If $\mathbf{v}_1, \dots, \mathbf{v}_n$ is an **orthogonal basis** of V , and \mathbf{x} is in V , then

$$\mathbf{x} = c_1\mathbf{v}_1 + \dots + c_n\mathbf{v}_n \quad \text{with} \quad c_j = \frac{\langle \mathbf{x}, \mathbf{v}_j \rangle}{\langle \mathbf{v}_j, \mathbf{v}_j \rangle}.$$

- Suppose that V is a subspace of W , and \mathbf{x} is in W , then the **orthogonal projection** of \mathbf{x} onto V is given by

$$\hat{\mathbf{x}} = c_1\mathbf{v}_1 + \dots + c_n\mathbf{v}_n \quad \text{with} \quad c_j = \frac{\langle \mathbf{x}, \mathbf{v}_j \rangle}{\langle \mathbf{v}_j, \mathbf{v}_j \rangle}.$$

- The basis $\mathbf{v}_1, \dots, \mathbf{v}_n$ has to be orthogonal for this formula!!
- This decomposes $\mathbf{x} = \underbrace{\hat{\mathbf{x}}}_{\text{in } V} + \underbrace{\mathbf{x}^\perp}_{\text{in } V^\perp}$, where the error \mathbf{x}^\perp is orthogonal to V . (this decomposition is unique)



- The corresponding **projection matrix** represents $\mathbf{x} \mapsto \hat{\mathbf{x}}$ with respect to the standard basis.

Example 1.

- (a) What is the orthogonal projection of $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ onto $\text{span}\left\{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right\}$?

Solution: The projection is $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$.

- (b) What is the orthogonal projection of $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ onto $\text{span}\left\{\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right\}$?

Solution: The projection is $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$.

Wrong approach!!
$$\frac{\langle \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \rangle}{\langle \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \rangle} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + \frac{\langle \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \rangle}{\langle \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \rangle} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

This is wrong because $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$ are not orthogonal. (See next example!)

- (c) What is the orthogonal projection of $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$ onto $\text{span}\left\{\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right\}$?

Solution: The projection is $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$.

Wrong!!
$$\frac{\langle \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \rangle}{\langle \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \rangle} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + \frac{\langle \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \rangle}{\langle \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \rangle} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + \frac{2}{3} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

Corrected: $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \implies \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ (for instance, using Gram–Schmidt)

$$\frac{\langle \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \rangle}{\langle \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \rangle} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + \frac{\langle \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \rangle}{\langle \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \rangle} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

- (d) What is the projection matrix corresponding to orthogonal projection onto $\text{span}\left\{\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}\right\}$?

Solution: The projection matrix is $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$.

What would Gram–Schmidt do? $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \implies \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

- (e) What is the orthogonal projection of $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ onto $\text{span}\left\{\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}\right\}$?

Solution: The projection is $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$.

- The space of all nice functions with period 2π has the natural inner product $\langle f, g \rangle = \int_0^{2\pi} f(x)g(x)dx$. [in \mathbb{R}^n : $\langle \mathbf{x}, \mathbf{y} \rangle = x_1y_1 + \dots + x_ny_n$]
- The functions

$$1, \cos(x), \sin(x), \cos(2x), \sin(2x), \dots$$

are an orthogonal basis for this space.

- Expanding a function $f(x)$ in this basis produces its **Fourier series**

$$f(x) = a_0 + a_1\cos(x) + b_1\sin(x) + a_2\cos(2x) + b_2\sin(2x) + \dots$$

Example 2. How can we compute b_2 ?

Solution.

$b_2\sin(2x)$ is the orthogonal projection of f onto the span of $\sin(2x)$.

Hence:

$$b_2 = \frac{\langle f(x), \sin(2x) \rangle}{\langle \sin(2x), \sin(2x) \rangle} = \frac{\int_0^{2\pi} f(x)\sin(2x)dx}{\int_0^{2\pi} \sin^2(2x)dx}$$

Least squares

- $\hat{\mathbf{x}}$ is a **least squares solution** of the system $A\mathbf{x} = \mathbf{b}$.
 - $\iff \hat{\mathbf{x}}$ is such that $A\hat{\mathbf{x}} - \mathbf{b}$ is as small as possible.
 - $\iff A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$ (the **normal equations**)

Example 3. Find the least squares line for the data points $(2, 1), (5, 2), (7, 3), (8, 3)$.

Solution.

Looking for β_1, β_2 such that the line $y = \beta_1 + \beta_2 x$ best fits the data.

The equations $y_i = \beta_1 + \beta_2 x_i$ in matrix form:

$$\underbrace{\begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ 1 & x_3 \\ 1 & x_4 \end{bmatrix}}_{\text{design matrix } X} \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} = \underbrace{\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}}_{\text{observation vector } \mathbf{y}}$$

Here, we need to find a least squares solution to

$$\begin{bmatrix} 1 & 2 \\ 1 & 5 \\ 1 & 7 \\ 1 & 8 \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix}.$$

$$X^T X = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 2 & 5 & 7 & 8 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 5 \\ 1 & 7 \\ 1 & 8 \end{bmatrix} = \begin{bmatrix} 4 & 22 \\ 22 & 142 \end{bmatrix}$$

$$X^T \mathbf{y} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 2 & 5 & 7 & 8 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix} = \begin{bmatrix} 9 \\ 57 \end{bmatrix}$$

Solving $\begin{bmatrix} 4 & 22 \\ 22 & 142 \end{bmatrix} \hat{\beta} = \begin{bmatrix} 9 \\ 57 \end{bmatrix}$, we find $\begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} = \begin{bmatrix} 2/7 \\ 5/14 \end{bmatrix}$.

Gram–Schmidt

Recipe. (Gram–Schmidt orthonormalization)

Given a basis $\mathbf{a}_1, \dots, \mathbf{a}_n$, produce an orthonormal basis $\mathbf{q}_1, \dots, \mathbf{q}_n$.

$$\begin{aligned} \mathbf{b}_1 &= \mathbf{a}_1, & \mathbf{q}_1 &= \frac{\mathbf{b}_1}{\|\mathbf{b}_1\|} \\ \mathbf{b}_2 &= \mathbf{a}_2 - \langle \mathbf{a}_2, \mathbf{q}_1 \rangle \mathbf{q}_1, & \mathbf{q}_2 &= \frac{\mathbf{b}_2}{\|\mathbf{b}_2\|} \\ \mathbf{b}_3 &= \mathbf{a}_3 - \langle \mathbf{a}_3, \mathbf{q}_1 \rangle \mathbf{q}_1 - \langle \mathbf{a}_3, \mathbf{q}_2 \rangle \mathbf{q}_2, & \mathbf{q}_3 &= \frac{\mathbf{b}_3}{\|\mathbf{b}_3\|} \\ & & & \vdots \end{aligned}$$

- An **orthogonal matrix** is a square matrix Q with orthonormal columns. Equivalently, $Q^T Q = I$ (also true for non-square matrices).
- Apply Gram–Schmidt to the (independent) columns of A to obtain the **QR decomposition** $A = QR$.
 - Q has orthonormal columns (the output vectors of Gram–Schmidt)
 - $R = Q^T A$ is upper triangular

Example 4. Find the QR decomposition of $A = \begin{bmatrix} 1 & 1 \\ 2 & 0 \\ 0 & 1 \end{bmatrix}$.

Solution. We apply Gram–Schmidt to the columns of A :

$$\frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} = \mathbf{q}_1$$

$$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} - \left\langle \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \mathbf{q}_1 \right\rangle \mathbf{q}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} - \frac{1}{\sqrt{5}} \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 4/5 \\ -2/5 \\ 1 \end{bmatrix}, \quad \frac{1}{\sqrt{9/5}} \begin{bmatrix} 4/5 \\ -2/5 \\ 1 \end{bmatrix} = \mathbf{q}_2$$

$$\text{Hence: } Q = [\mathbf{q}_1 \quad \mathbf{q}_2] = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{4}{\sqrt{45}} \\ \frac{2}{\sqrt{5}} & -\frac{2}{\sqrt{45}} \\ 0 & \frac{5}{\sqrt{45}} \end{bmatrix}$$

$$\text{And: } R = Q^T A = \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} & 0 \\ \frac{4}{\sqrt{45}} & -\frac{2}{\sqrt{45}} & \frac{5}{\sqrt{45}} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} \frac{5}{\sqrt{5}} & \frac{1}{\sqrt{5}} \\ 0 & \frac{9}{\sqrt{45}} \end{bmatrix}$$

Determinants

- A is invertible $\iff \det(A) \neq 0$
- $\det(AB) = \det(A)\det(B)$
- $\det(A^{-1}) = \frac{1}{\det(A)}$
- $\det(A^T) = \det(A)$
- The **determinant** is characterized by:
 - the normalization $\det I = 1$,
 - and how it is affected by elementary row operations:
 - **(replacement)** Add one row to a multiple of another row.
Does not change the determinant.
 - **(interchange)** Interchange two rows.
Reverses the sign of the determinant.
 - **(scaling)** Multiply all entries in a row by s .
Multiplies the determinant by s .

$$\begin{vmatrix} 1 & 2 & 3 & 4 \\ 0 & 2 & 1 & 5 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 3 & 5 \end{vmatrix} \xrightarrow{R4 \rightarrow R4 - \frac{3}{2}R3} = \begin{vmatrix} 1 & 2 & 3 & 4 \\ 0 & 2 & 1 & 5 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & \frac{7}{2} \end{vmatrix} = 1 \cdot 2 \cdot 2 \cdot \frac{7}{2} = 14$$

- **Cofactor expansion** is another way to compute determinants.

$$\begin{vmatrix} 1 & 2 & 0 \\ 3 & -1 & 2 \\ 2 & 0 & 1 \end{vmatrix} = -2 \cdot \begin{vmatrix} 3 & 2 \\ 2 & 1 \end{vmatrix} + (-1) \cdot \begin{vmatrix} 1 & 0 \\ 2 & 1 \end{vmatrix} - 0 \cdot \begin{vmatrix} 1 & 3 \\ 3 & 2 \end{vmatrix} \\ = -2 \cdot (-1) + (-1) \cdot 1 - 0 = 1$$

Example 5. What is $\begin{vmatrix} 1 & 1 & 1 & 4 \\ -1 & 2 & 2 & 5 \\ 0 & 3 & 3 & 1 \\ 2 & 0 & 0 & 5 \end{vmatrix}$?

Solution. The determinant is 0 because the matrix is not invertible (second and third column are the same).

Eigenvalues and eigenvectors

- If $A\mathbf{x} = \lambda\mathbf{x}$, then \mathbf{x} is an **eigenvector** of A with **eigenvalue** λ .
- λ is an eigenvalue of $A \iff \underbrace{\det(A - \lambda I)}_{\text{characteristic polynomial}} = 0$.

Why? Because $A\mathbf{x} = \lambda\mathbf{x} \iff (A - \lambda I)\mathbf{x} = \mathbf{0}$.

- The **eigenspace** of λ is $\text{Nul}(A - \lambda I)$.
It consists of all eigenvectors (plus $\mathbf{0}$) with eigenvalue λ .
- Eigenvectors $\mathbf{x}_1, \dots, \mathbf{x}_m$ of A corresponding to different eigenvalues are independent.
- Useful for checking: sum of eigenvalues = sum of diagonal entries