

The geometry of linear equations

Adding and scaling vectors

Example 1. We have already encountered **matrices** such as

$$\begin{bmatrix} 1 & 4 & 2 & 3 \\ 2 & -1 & 2 & 2 \\ 3 & 2 & -2 & 0 \end{bmatrix}.$$

Each column is what we call a **(column) vector**.

In this example, each column vector has 3 entries and so lies in \mathbb{R}^3 .

Example 2. A fundamental property of vectors is that vectors of the same kind can be **added** and **scaled**.

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix} = \quad , \quad 7 \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \quad .$$

Example 3. (Geometric description of \mathbb{R}^2) A vector $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ represents the point (x_1, x_2) in the plane.

Given $\mathbf{x} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$ and $\mathbf{y} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$, graph \mathbf{x} , \mathbf{y} , $\mathbf{x} + \mathbf{y}$, $3\mathbf{x}$.

Adding and scaling vectors, the most general thing we can do is:

Definition 4. Given vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ in \mathbb{R}^n and scalars c_1, c_2, \dots, c_m , the vector

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_m\mathbf{v}_m$$

is a **linear combination** of $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$.

The scalars c_1, \dots, c_m are the **coefficients** or **weights**.

Example 5. Linear combinations of $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ include:

- $3\mathbf{v}_1 - \mathbf{v}_2 + 7\mathbf{v}_3$,
- $\frac{1}{3}\mathbf{v}_2$,
- $\mathbf{v}_2 + \mathbf{v}_3$,
- 0 .

Example 6. Express $\begin{bmatrix} 1 \\ 5 \end{bmatrix}$ as a linear combination of $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$.

Solution. We have to find c_1 and c_2 such that ...

The row and column picture

Example 7. We can think of the linear system

$$\begin{aligned}2x - y &= 1 \\ x + y &= 5\end{aligned}$$

in two different geometric ways.

Row picture.

Each equation defines a line in \mathbb{R}^2 .

Which points lie on the intersection of these lines?

Column picture.

The system can be written as $x \begin{bmatrix} 2 \\ 1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \end{bmatrix}$.

Which linear combinations of $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$ produce $\begin{bmatrix} 1 \\ 5 \end{bmatrix}$?

This example has the unique solution $x = 2$, $y = 3$.

- $(2, 3)$ is the (only) intersection of the two lines $2x - y = 1$ and $x + y = 5$.
- $2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ is the (only) linear combination producing $\begin{bmatrix} 1 \\ 5 \end{bmatrix}$.

Example 8. Consider the vectors

$$\mathbf{a}_1 = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}, \quad \mathbf{a}_2 = \begin{bmatrix} 4 \\ 2 \\ 14 \end{bmatrix}, \quad \mathbf{a}_3 = \begin{bmatrix} 3 \\ 6 \\ 10 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} -1 \\ 8 \\ -5 \end{bmatrix}.$$

Determine if \mathbf{b} is a linear combination of $\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3$.

Solution. Vector \mathbf{b} is a linear combination of $\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3$ if we can find weights x_1, x_2, x_3 such that:

This vector equation corresponds to the linear system:

Corresponding augmented matrix:

Row reduction to echelon form:

Hence:

Example 9. In the previous example, express \mathbf{b} as a linear combination of $\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3$.

Solution.

Summary

A vector equation

$$x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \dots + x_m\mathbf{a}_m = \mathbf{b}$$

has the same solution set as the linear system with augmented matrix

$$\left[\begin{array}{c|c|c|c|c} | & | & & | & | \\ \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_m & \mathbf{b} \\ | & | & & | & | \end{array} \right].$$

In particular, \mathbf{b} can be generated by a linear combination of $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_m$ if and only if there is a solution to this linear system.

The span of a set of vectors

Definition 10. The **span** of vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ is the set of all their linear combinations. We denote it by $\text{span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m\}$.

In other words, $\text{span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m\}$ is the set of all vectors of the form

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_m\mathbf{v}_m,$$

where c_1, c_2, \dots, c_m are scalars.

Example 11.

(a) Describe $\text{span}\left\{\begin{bmatrix} 2 \\ 1 \end{bmatrix}\right\}$ geometrically.

(b) Describe $\text{span}\left\{\begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ 1 \end{bmatrix}\right\}$ geometrically.

(c) Describe $\text{span}\left\{\begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ 2 \end{bmatrix}\right\}$ geometrically.

A single (nonzero) vector always spans a line, two vectors $\mathbf{v}_1, \mathbf{v}_2$ usually span a plane but it could also be just a line (if $\mathbf{v}_2 = \alpha\mathbf{v}_1$).

We will come back to this when we discuss dimension and linear independence.

Example 12. Is $\text{span}\left\{\begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ -2 \\ 1 \end{bmatrix}\right\}$ a line or a plane?

Solution.

Example 13. Consider

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 1 \\ 0 & 5 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 8 \\ 3 \\ 17 \end{bmatrix}.$$

Is \mathbf{b} in the plane spanned by the columns of A ?

Solution.

Conclusion and summary

- The **span** of vectors $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_m$ is the set of all their **linear combinations**.
- Some vector \mathbf{b} is in $\text{span}\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_m\}$ if and only if there is a solution to the linear system with augmented matrix

$$\left[\begin{array}{c|c|c|c|c|c} | & | & & | & | & \\ \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_m & \mathbf{b} & \\ | & | & & | & | & \end{array} \right].$$

- Each solution corresponds to the weights in a linear combination of the $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_m$ which gives \mathbf{b} .
- This gives a second geometric way to think of linear systems!