Sketch of Lecture 8

We never write $\frac{A}{B}$ for matrices! Why?

Because it is unclear whether you mean AB^{-1} or $B^{-1}A$. (And order matters a lot with matrices!)

7.1 Recipe for computing the inverse of any matrix

To compute A^{-1} :

- Form the augmented matrix [A | I].
- Compute the reduced echelon form.
- If A is invertible, the RREF is of the form $\begin{bmatrix} I & A^{-1} \end{bmatrix}$.

Why is that reasonable?

- Well, to solve $A\mathbf{x} = \mathbf{b}$, we do row reduction on $[A \mid \mathbf{b}]$.
- Likewise, to solve AX = I (to find the inverse X), we do row reduction on $\begin{bmatrix} A & I \end{bmatrix}$.

Example 59. Find the inverse of $A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, if it exists.

Solution. We compute the RREF of $[A \mid I]$:

$$\begin{bmatrix} 1 & 0 & 0 & | & 1 & 0 & 0 \\ 2 & 1 & 0 & | & 0 & 1 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2 - 2R_1 \Rightarrow R_2} \begin{bmatrix} 1 & 0 & 0 & | & 1 & 0 & 0 \\ 0 & 1 & 0 & | & -2 & 1 & 0 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix}$$

Hence,
$$\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Comment. When computing any product BA, the matrix BA is obtained from B by the single column operation $C_1 + 2C_2 \Rightarrow C_1$ (why?!). That's the effect of multiplication with A (on the right). This can be "undone" by the single column operation $C_1 - 2C_2 \Rightarrow C_1$. The corresponding matrix is A^{-1} .

Example 60. Find the inverse of $A = \begin{bmatrix} 2 & 0 & 0 \\ -3 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$, if it exists.

Solution. We compute the RREF of $[A \mid I]$:

$$\begin{bmatrix} 2 & 0 & 0 & | & 1 & 0 & 0 \\ -3 & 0 & 1 & 0 & | & 0 & 1 & 0 \\ 0 & 1 & 0 & | & 0 & 0 & 1 \end{bmatrix} R_{2} + \frac{3}{2}R_{1} \Rightarrow R_{2} \begin{bmatrix} 2 & 0 & 0 & | & 1 & 0 & 0 \\ 0 & 0 & 1 & \frac{3}{2} & 1 & 0 \\ 0 & 1 & 0 & | & 0 & 0 & 1 \end{bmatrix}^{\frac{1}{2}R_{1} \Rightarrow R_{1}} \begin{bmatrix} 1 & 0 & 0 & | & \frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 & \frac{3}{2} & 1 & 0 \end{bmatrix}$$

Hence, $A^{-1} = \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 \\ \frac{3}{2} & 1 & 0 \end{bmatrix}$. [We can easily check that: $\begin{bmatrix} 2 & 0 & 0 \\ -3 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 \\ \frac{3}{2} & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$]

Armin Straub straub@southalabama.edu Gauss-Jordan method

(i.e. Gauss-Jordan elimination)

Example 61. Solve $\begin{bmatrix} 2 & 0 & 0 \\ -3 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$. Then, solve $\begin{bmatrix} 2 & 0 & 0 \\ -3 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \mathbf{x} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$.

Solution. From the previous problem, we know that the matrix $A = \begin{bmatrix} 2 & 0 & 0 \\ -3 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$ is invertible. Using its inverse, we find that (review Theorem 57)

$$\boldsymbol{x} = A^{-1}\boldsymbol{b} = \begin{bmatrix} \frac{1}{2} & 0 & 0\\ 0 & 0 & 1\\ \frac{3}{2} & 1 & 0 \end{bmatrix} \begin{bmatrix} 1\\ 0\\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2}\\ 1\\ \frac{3}{2} \end{bmatrix}$$

is the unique solution.

Likewise, for the second system, we have the unique solution

$$\boldsymbol{x} = \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 \\ \frac{3}{2} & 1 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix}.$$

Important practical observation. Note how easy it is now (once we have the inverse) to solve linear systems for various right-hand sides.

7.2 The inverse of a 2×2 matrix

The following formula immediately gives us the inverse of a 2×2 matrix (if it exists). It is worth remembering!

$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$	provided that $ad - bc \neq 0$
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Let's check that! $\frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \frac{1}{ad-bc} \begin{bmatrix} ad-bc & 0 \\ 0 & -cb+ad \end{bmatrix} = I_2$

Note.

- A 1×1 matrix [a] is invertible $\iff a \neq 0$.
- A 2×2 matrix $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is invertible $\iff ad bc \neq 0$.

We will later see that the quantities on the RHS are the **determinants** of these matrices.

Example 62. Solve
$$\begin{bmatrix} -7 & 3 \\ 5 & -2 \end{bmatrix} x = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$
 by inverting the matrix.

Solution. We multiply both sides with the inverse of $\begin{bmatrix} -7 & 3 \\ 5 & -2 \end{bmatrix}$.

 $\left[\text{In the process of doing so, we see that the inverse does exist.} \right]$

Using the formula for 2×2 matrices:

$$\boldsymbol{x} = \begin{bmatrix} -7 & 3\\ 5 & -2 \end{bmatrix}^{-1} \begin{bmatrix} 2\\ 1 \end{bmatrix} = \frac{1}{14 - 15} \begin{bmatrix} -2 & -3\\ -5 & -7 \end{bmatrix} \begin{bmatrix} 2\\ 1 \end{bmatrix} = \begin{bmatrix} 7\\ 17 \end{bmatrix}$$

Armin Straub straub@southalabama.edu