## **Sketch of Lecture 11**

**Example 79.** Consider the matrices  $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ -2 & 4 \end{bmatrix}$  and  $B = \begin{bmatrix} 1 & 2 \\ 3 & 0 \end{bmatrix}$ . Compute: (a)  $AB = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ -2 & 4 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 0 \end{bmatrix} =$ (b)  $(AB)^T =$ (c)  $B^T A^T = \begin{bmatrix} 1 & 3 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & -2 \\ 2 & 1 & 4 \end{bmatrix} =$ (d)  $A^T B^T = \begin{bmatrix} 1 & 0 & -2 \\ 2 & 1 & 4 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 2 & 0 \end{bmatrix} =$ What's that fishy smell?

**Theorem 80.** Let A, B be matrices of appropriate size. Then:

•	$(A^T)^T = A$	οbνίοι	ıs!
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- $(A+B)^T = A^T + B^T$ obvious!
- $(AB)^T = B^T A^T$ (illustrated by the previous example)
- $(A^T)^{-1} = (A^{-1})^T$ Why? Do you see how this follows from the previous item?
- $\det(A^T) = \det(A)$

**Example 81.** Let A and B be  $n \times n$  matrices with det(A) = a and det(B) = b. Simplify  $\det(3A^T A B^2 A^{-1}).$ 

**Solution.**  $det(3A^TAB^2A^{-1}) = 3^n det(A^TAB^2A^{-1}) = 3^n det(A^T) det(A) det(B^2) det(A^{-1}) = 3^n ab^2$ 

## Linear independence 10

**Definition 82.** Vectors  $v_1, v_2, ..., v_n$  are (linearly) dependent if

$$x_1 \boldsymbol{v}_1 + x_2 \boldsymbol{v}_2 + \ldots + x_n \boldsymbol{v}_n = \boldsymbol{0}$$

for some  $x_i$ , not all zero.

[This is then called a linear dependence relation.]

[There is always the trivial linear combination in which all coefficients are 0:  $x_1 = 0, x_2 = 0, ..., x_n = 0$ .] Otherwise, the vectors are (linearly) independent.

**Example 83.** Are the vectors  $\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}$ ,  $\begin{bmatrix} 1\\2\\3\\3 \end{bmatrix}$ ,  $\begin{bmatrix} -1\\1\\3\\3 \end{bmatrix}$  linearly independent?

Solution. We need to find out if

$$x_1 \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix} + x_2 \begin{bmatrix} 1\\2\\3\\\end{bmatrix} + x_3 \begin{bmatrix} -1\\1\\3\\3 \end{bmatrix} = \begin{bmatrix} 0\\0\\0 \end{bmatrix}$$

has any solutions besides the trivial solution  $x_1 = x_2 = x_3 = 0$ . But that's just asking whether a linear system (which is obviously consistent; why?!) has a unique solution or whether there are infinitely many solutions. We therefore eliminate:

$$\begin{bmatrix} 1 & 1 & -1 & 0 \\ 1 & 2 & 1 & 0 \\ 1 & 3 & 3 & 0 \end{bmatrix} \xrightarrow{R_2 - R_1 \Rightarrow R_2}_{R_3 - R_1 \Rightarrow R_3} \begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 2 & 4 & 0 \end{bmatrix} \xrightarrow{R_3 - 2R_2 \Rightarrow R_3}_{R_3 - 2R_2 \Rightarrow R_3} \begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

From the echelon form, we see that the system is consistent (it had to be!) and that it has infinitely many solutions (because there is a free variable).

Hence, our three vectors are not linearly independent.

Exhibit a linear dependence relation among the vectors  $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ ,  $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ ,  $\begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$ .

Solution. We have already done the bulk of the work in the previous problem.

For a change, let us solve the system by back-substitution.  $x_3 = s_1$  is free. Then,  $x_2 = -2s_1$  and  $x_1 = -x_2 + x_3 = 3s_1$ . This means that

 $3s_1 \begin{bmatrix} 1\\1\\1 \end{bmatrix} - 2s_1 \begin{bmatrix} 1\\2\\3 \end{bmatrix} + s_1 \begin{bmatrix} -1\\1\\3 \end{bmatrix} = \begin{bmatrix} 0\\0\\0 \end{bmatrix}.$ 

This is a non-trivial linear combination of our three vectors which produces the zero vector.

Note that setting  $s_1 = 1$  produces a nice linear combination, and that every other linear combination is just a multiple.

**Example 84.** With the minimum amount of work, decide whether the following vectors are linearly independent.

(a)  $\begin{bmatrix} 2\\0\\0 \end{bmatrix}$ ,  $\begin{bmatrix} -1\\1\\0 \end{bmatrix}$ ,  $\begin{bmatrix} 3\\7\\3 \end{bmatrix}$  Solution. These vectors are linearly independent.

Put them as columns of a matrix, and notice that this matrix is already in echelon form...

(b)  $\begin{bmatrix} 3\\2\\1 \end{bmatrix}$ ,  $\begin{bmatrix} 9\\6\\4 \end{bmatrix}$  Solution. These vectors are linearly independent.

If they were dependent, then  $x_1\begin{bmatrix}3\\2\\1\end{bmatrix} + x_2\begin{bmatrix}9\\6\\4\end{bmatrix} = 0$ . Since  $x_1 \neq 0$  (why?),  $\begin{bmatrix}3\\2\\1\end{bmatrix} = -\frac{x_2}{x_1}\begin{bmatrix}9\\6\\4\end{bmatrix}$  so that the second vector would be a multiple of the first. But it isn't! (Judging by the first entry, the second vector would have to be 3 times the first; but that clashes with the third entry.)

**Moral.** two vectors are linearly dependent  $\iff$  one is a multiple of the other

(c)  $\begin{bmatrix} 2\\0\\0 \end{bmatrix}$ ,  $\begin{bmatrix} 0\\0\\0 \end{bmatrix}$  Solution. These vectors are linearly dependent. For instance,  $0\begin{bmatrix} 2\\0\\0 \end{bmatrix} + 7\begin{bmatrix} 0\\0\\0 \end{bmatrix} = \begin{bmatrix} 0\\0\\0 \end{bmatrix}$  is a non-trivial dependence relation (the coefficients are 0 and 7).

Moral. Whenever the zero vector is involved, the vectors are linearly dependent.