**Example 106.** Let  $A = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ . What is rank(A)? Find a basis for col(A), row(A), null(A).

**Solution.**  $\operatorname{rank}(A) = 2$ . Hence,  $\dim \operatorname{col}(A) = \dim \operatorname{row}(A) = 2$  and  $\dim \operatorname{null}(A) = 3 - 2 = 1$ . The dimension of  $\operatorname{null}(A)$  is also called the **nullity** of A.

- A basis for col(A) is:  $\begin{bmatrix} 1\\0\\1 \end{bmatrix}$ ,  $\begin{bmatrix} 0\\1 \end{bmatrix}$
- A basis for row(A) is:  $\begin{bmatrix} 1\\ 2\\ 0 \end{bmatrix}$ ,  $\begin{bmatrix} 0\\ 0\\ 1 \end{bmatrix}$
- A basis for null(A) is:  $\begin{bmatrix} -2\\1\\0 \end{bmatrix}$

**Example 107.** Let  $A = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ . What is rank(A)? Find a basis for col(A), row(A), null(A).

Solution.

- A basis for col(A) is:  $\begin{bmatrix} 1\\ 2\\ 3 \end{bmatrix}$ . In particular, rank(A) = 1.
- A basis for row(A) is: [1]
- $\dim \operatorname{null}(A) = 1 1 = 0$ . A basis for  $\operatorname{null}(A)$  is: {} (the empty set; this basis consists of 0 zero vectors)

Note. Make sure that all of these are evident to you, without computations.

If we insist on computing, the RREF of A is  $\begin{bmatrix} 1\\0\\0 \end{bmatrix}$  and, using Theorem 99, we end up with the same bases.

**Example 108.** Determine a basis for  $W = \operatorname{span}\left\{ \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}, \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} -1\\1\\3 \end{bmatrix} \right\}.$ 

Note that we have two choices because we can

- use Theorem 99(a) to determine a basis for  $W = \operatorname{col}\left(\begin{bmatrix} 1 & 1 & -1 \\ 1 & 2 & 1 \\ 1 & 3 & 3 \end{bmatrix}\right)$ , or
- use Theorem 99(b) to determine a basis for  $W = \operatorname{col}\left(\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ -1 & 1 & 3 \end{bmatrix}\right)$ .

The first option will produce a basis from a subset of the original spanning vectors, while the second option will introduce new vectors (with some zeros). The amount of computation is the same.

Solution. Note that W = col(A) with  $A = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 2 & 1 \\ 1 & 3 & 3 \end{bmatrix}$ . Since  $\begin{bmatrix} 1 & 1 & -1 \\ 1 & 2 & 1 \\ 1 & 3 & 3 \end{bmatrix} \overset{R_2 - R_1 \Rightarrow R_2}{\underset{\longrightarrow}{R_3 - R_1 \Rightarrow R_3}} \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 2 \\ 0 & 2 & 4 \end{bmatrix} \overset{R_3 - 2R_2 \Rightarrow R_3}{\underset{\longrightarrow}{K_3 - R_3 \Rightarrow R_3}} \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$ , a basis for W is  $\begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \\ 3 \end{bmatrix}$ .

Note. Recall that bases are not at all unique. For instance, now that we know that W is 2-dimensional, we see that any pair of its original spanning vectors would form a basis (because each such pair is linearly independent).

Solution. Note that  $W = \operatorname{row}(A)$  with  $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ -1 & 1 & 3 \end{bmatrix}$ . Since  $\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ -1 & 1 & 3 \end{bmatrix} \xrightarrow{R_2 - R_1 \Rightarrow R_2}_{R_3 + R_1 \Rightarrow R_3} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 2 & 4 \end{bmatrix} \xrightarrow{R_3 - 2R_2 \Rightarrow R_3} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix},$ a basis for W is  $\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}, \begin{bmatrix} 0\\1\\2 \end{bmatrix}$ .

Note. In this case, we get a basis that is not taken from the original spanning vectors. Here, we can still see how it is related to the basis we obtained earlier:  $\begin{bmatrix} 1\\2\\3\\1\\1 \end{bmatrix} = \begin{bmatrix} 1\\1\\1\\1\\2 \end{bmatrix} = \begin{bmatrix} 1\\0\\2\\2\\2 \end{bmatrix}$ .

Recall that a basis of V is a list of vectors in V, which span V and which are linearly independent. The following is a rephrasing of that:

Vectors  $\boldsymbol{v}_1, ..., \boldsymbol{v}_d$  in V are a basis of V. Every vector in V can be written uniquely as a linear combination of  $v_1, ..., v_d$ .

Why? "can be written" because a basis spans V. "uniquely" because basis vectors are linearly independent.

**Example 109.** Let W be as in the previous example. Is  $\begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}$  in W? Is  $\begin{bmatrix} 2 \\ 0 \\ -2 \end{bmatrix}$  in W?

Answer using each of the bases we have constructed. If a vector is in W, then write it in terms of the basis.

**Solution.** We use the basis  $\alpha$ :  $\begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 2 \\ 2 \end{bmatrix}$ . [ $\alpha$  is just a random name for this basis to distinguish it from the second one]

Since  $\begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 1 \\ 1 & 3 & -2 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & -1 \\ 0 & 2 & -4 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & -2 \end{bmatrix}$  is inconsistent,  $\begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}$  is not in W.

On the other hand,  $\begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 0 \\ 1 & 3 & -2 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & -2 \\ 0 & 2 & -4 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix}$  is consistent. So,  $\begin{bmatrix} 2 \\ 0 \\ -2 \end{bmatrix}$  is in W.

 $\begin{bmatrix} 2\\0\\-2 \end{bmatrix} = 4 \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix} - 2 \begin{bmatrix} 1\\2\\3\\3 \end{bmatrix}$ . Instead of  $\begin{bmatrix} 2\\0\\-2 \end{bmatrix}$ , we can write  $\begin{bmatrix} 4\\-2\\ \end{bmatrix}_{\alpha}$ . Allows us to work with W as if it was  $\mathbb{R}^2$ .

**Solution.** We use the basis  $\beta$ :  $\begin{bmatrix} 1\\1\\1\\1 \end{bmatrix}$ ,  $\begin{bmatrix} 0\\1\\2 \end{bmatrix}$ . We find, again, that  $\begin{bmatrix} 2\\1\\-2 \end{bmatrix}$  is not in W, and that  $\begin{bmatrix} 2\\0\\-2 \end{bmatrix}$  is in W.

Do it! You can proceed exactly as before. But you can also try to exploit the extra 0 in the basis to avoid row operations

This time,  $\begin{bmatrix} 2\\0\\-2 \end{bmatrix} = 2 \begin{bmatrix} 1\\1\\1\\-2 \end{bmatrix} - 2 \begin{bmatrix} 0\\1\\2 \end{bmatrix}$ . Instead of  $\begin{bmatrix} 2\\0\\-2 \end{bmatrix}$ , we can now write  $\begin{bmatrix} 2\\-2\\-2 \end{bmatrix}_{\beta}$ .